

MAKING MODERN LIVING POSSIBLE



Quick Reference Guide

VLT® AQUA Drive FC 200

Electrical Overview

Illustration 2.4 shows a basic electrical connection.

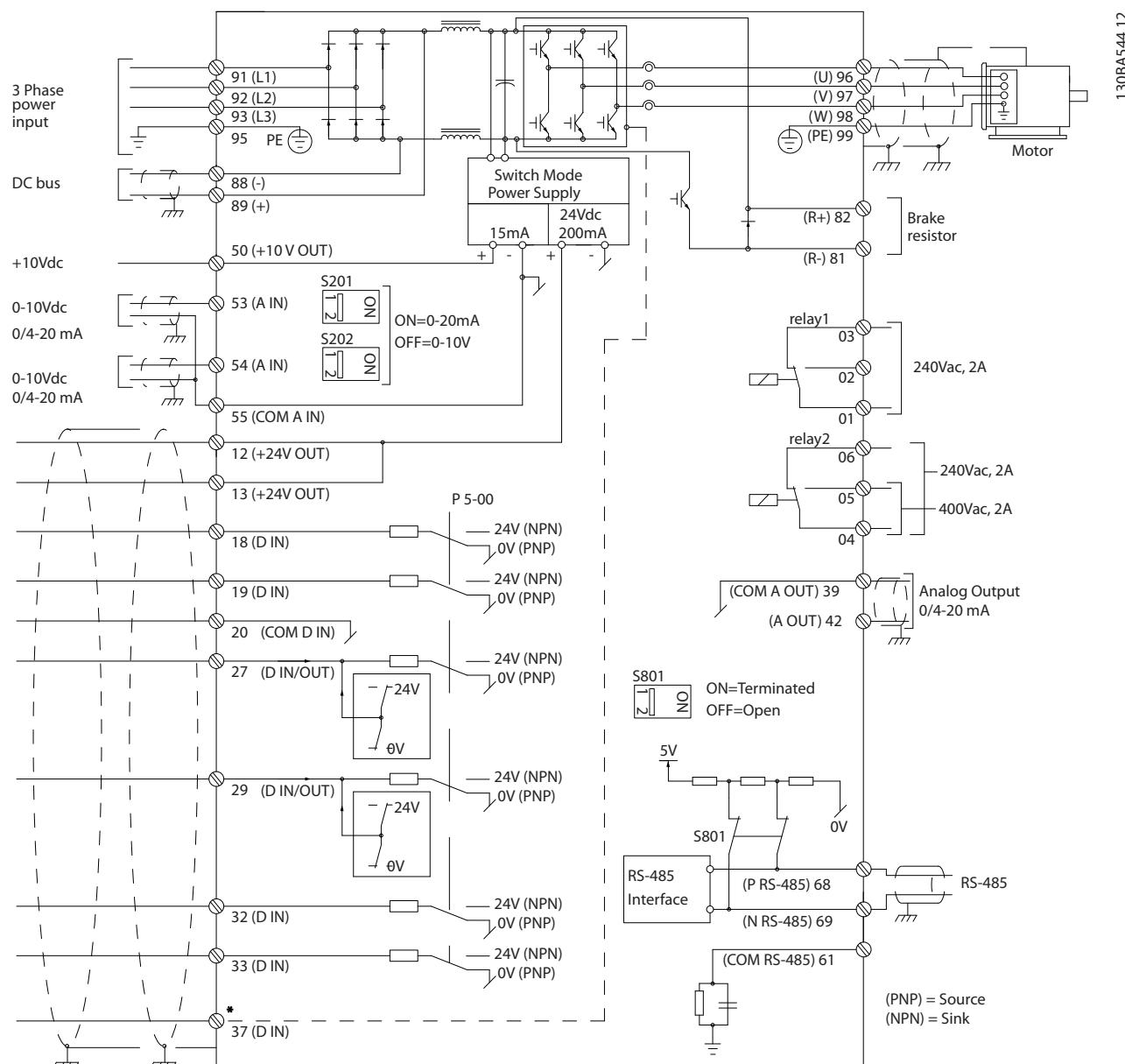


Illustration 2.4 Basic Wiring Schematic Drawing.

* Terminal 37 is an option

How to Programme

Local Control Panel

The local control panel (LCP) is the combined display and keypad on the front of the unit. The LCP is the user interface to the frequency converter.

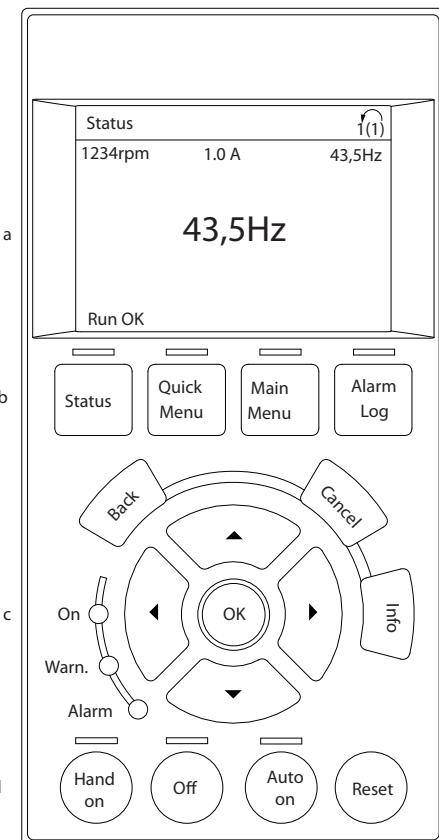
The LCP has several user functions.

- Start, stop, and control speed when in local control
- Display operational data, status, warnings and cautions
- Programming frequency converter functions
- Manually reset the frequency converter after a fault when auto-reset is inactive

An optional numeric LCP (NLCP) is also available. The NLCP operates in a manner similar to the LCP. See the *Programming Guide*, for details on use of the NLCP.

LCP Layout

The LCP is divided into four functional groups (see *Illustration 4.1*).



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Illustration 4.1 LCP

- a. Display area.
- b. Display menu keys for changing the display to show status options, programming, or error message history.
- c. Navigation keys for programming functions, moving the display cursor, and speed control in local operation. Also included are the status indicator lights.
- d. Operational mode keys and reset.

Quick Menu Structure

Q2 Quick Setup	0-37 Display Text 1	20-12 Reference/Feedback Unit	Trending Comparison
0-01 Language	0-38 Display Text 2	3-02 Minimum Reference	Q7 Water and Pumps
0-02 Motor Speed Unit	0-39 Display Text 3	3-03 Maximum Reference	Q7-1 Pipe Fill
1-20 Motor Power [kW]	Q3-12 Analog Output	6-20 Terminal 54 Low Voltage	Q7-10 Horizontal Pipes
1-22 Motor Voltage	6-50 Terminal 42 Output	6-21 Terminal 54 High Voltage	29-00 Pipe Fill Enable
1-23 Motor Frequency	6-51 Terminal 42 Output Min Scale	6-24 Terminal 54 Low Ref./Feedb.	29-01 Pipe Fill Speed [RPM]
1-24 Motor Current	6-52 Terminal 42 Output Max Scale	6-25 Terminal 54 High Ref./Feedb.	29-02 Pipe Fill Speed [Hz]
1-25 Motor Nominal Speed	Q3-13 Relays Option relays if applicable	6-00 Live Zero Timeout Time	29-03 Pipe Fill Time
3-41 Ramp 1 Ramp Up Time	Relay 1 => 5-40 Function Relay	6-01 Live Zero Timeout Function	29-04 Pipe Fill Rate
3-42 Ramp 1 Ramp Down Time	Relay 2 => 5-40 Function Relay	Q3-31 PID Settings	29-05 Filled Setpoint
4-11 Motor Speed Low Limit [RPM]	Q3-2 Open Loop Settings	20-81 PID Normal/ Inverse Control	29-05 Filled Setpoint
4-13 Motor Speed High Limit [RPM]	Q3-20 Digital Reference	20-82 PID Start Speed [RPM]	29-06 No-Flow Disable Timer
1-29 Automatic Motor Adaptation (AMA)	3-02 Minimum Reference	20-21 Setpoint 1	Q7-11 Vertical Pipes
Q3 Function Setup	3-03 Maximum Reference	20-93 PID Proportional Gain	29-00 Pipe Fill Enable
Q3-1 General Settings	3-10 Preset Reference	20-94 PID Integral Time	29-04 Pipe Fill Rate
Q3-10 Clock Settings	5-13 Terminal 29 Digital Input	Q5 Changes Made	29-05 Filled Setpoint
0-70 Date and Time	5-14 Terminal 32 Digital Input	Q5-1 Last 10 Changes	29-06 No-Flow Disable Timer
0-71 Date Format	5-15 Terminal 33 Digital Input	Q5-2 Since Factory Setting	Q7-12 Mixed Systems
0-72 Time Format	Q3-21 Analog Reference	Q5-3 Input Assignments	29-00 Pipe Fill Enable
0-74 DST/Summertime	3-02 Minimum Reference	Q6 Loggings	29-01 Pipe Fill Speed [RPM]
0-76 DST/Summertime Start	3-03 Maximum Reference	Reference [Unit]	29-02 Pipe Fill Speed [Hz]
0-77 DST_Summertime End	6-10 Terminal 53 Low Voltage	Analog Input 53	29-03 Pipe Fill Time
Q3-11 Display Settings	6-11 Terminal 53 High Voltage	Motor current	29-05 Filled Setpoint
0-20 Display Line 1.1 Small	6-14 Terminal 53 Low Ref./Feedb.	Frequency	Q7-5 Sleep Mode
0-21 Display Line 1.2 Small	Value	29-06 No-Flow Disable Timer	Q7-50 Low Speed
		Feedback [Unit]	Q7-2 Deragging
			22-22 Low Speed Detection
0-22 Display Line 1.3 Small	Q3-3 Closed Loop Settings	Energy Log	22-23 No-Flow Function
0-23 Display Line 2 Large	Q3-30 Feedback Settings	Trending Cont Bin	22-24 No-Flow Delay
0-24 Display Line 3 Large	1-00 Configuration Mode	Trending Timed Bin	22-28 No-Flow Low Speed [RPM]

Table 5.2 Quick Menu Structure

			Q7-6 Flow Compensation	22-90 Flow at Rated Speed
22-29 No-Flow Low Speed [Hz]	22-24 No-Flow Delay	22-20 Low Power Auto Set-up		
22-40 Minimum Run Time	22-20 Low Power Auto Set-up	22-22 Low Speed Detection	22-80 Flow Compensation	Q7-7 Special Ramps
22-41 Minimum Sleep Time	22-40 Minimum Run Time	22-28 No-Flow Low Speed [RPM]	22-81 Square-linear Curve Approximation	3-84 Initial Ramp Time
22-42 Wake-up Speed [RPM]	22-41 Minimum Sleep Time	22-29 No-Flow Low Speed [Hz]	22-82 Work Point Calculation	3-88 Final Ramp Time
22-43 Wake-up Speed [Hz]	22-42 Wake-up Speed [RPM]	22-40 Minimum Run Time	22-83 Speed at No-Flow [RPM]	3-85 Check Valve Ramp Time
22-44 Wake-up Ref./FB Difference	22-43 Wake-up Speed [Hz]	22-41 Minimum Sleep Time	22-84 Speed at No-Flow [Hz]	3-86 Check Valve Ramp End Speed [RPM]
22-45 Setpoint Boost	22-44 Wake-up Ref./FB Difference	22-42 Wake-up Speed [RPM]	22-85 Speed at Design Point [RPM]	3-87 Check Valve Ramp End Speed [Hz]
22-46 Maximum Boost Time	22-45 Setpoint Boost	22-43 Wake-up Speed [Hz]	22-86 Speed at Design Point [Hz]	
Q7-51 Low Power	22-46 Maximum Boost Time	22-44 Wake-up Ref./FB Difference	22-87 Pressure at No-Flow Speed	
22-21 Low Power Detection	Q7-52 Low Speed/Power	22-45 Setpoint Boost	22-88 Pressure at Rated Speed	
22-23 No-Flow Function	22-21 Low Power Detection	22-46 Maximum Boost Time	22-89 Flow at Design Point	

Table 5.3

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Main Menu Structure

0-89 Date and Time Readout	1-** Load and Motor	1-8*	Stop Adjustments	3-93 Maximum Limit
1-0*	General Settings	1-80 Function at Stop	3-94 Minimum Limit	5-53 Term. 29 High Ref/Feedb. Value
1-00 Configuration Mode	1-81 Min Speed for Function at Stop [RPM]	3-95 Pulse Filter Time Constant #29	5-54 Term. 33 Low Frequency	
1-01 Motor Control Principle	1-82 Trip Speed [Hz]	3-95 Ramp Delay	5-55 Term. 33 High Frequency	
1-03 Torque Characteristics	1-86 Trip Speed Low [RPM]	4-** Motor Limits	5-56 Term. 33 Low Ref/Feedb. Value	
1-06 Clockwise Direction	1-87 Trip Speed Low [Hz]	4-1* Motor Limits	5-57 Term. 33 High Ref/Feedb. Value	
1-1*	Motor Selection	1-9* Motor Temperature	5-58 Term. 33 High Ref/Feedb. Value	
1-10 Motor Construction	1-90 Motor Thermal Protection	4-10 Motor Speed Direction	5-59 Pulse Filter Time Constant #33	
1-11 W+ PM	1-91 Motor External Fan	4-11 Motor Speed Low Limit [RPM]	5-6* Pulse Output	
1-12 Damping Gain	1-93 Thermistor Source	4-12 Motor Speed Low Limit [Hz]	5-60 Terminal 27 Pulse Output Variable	
1-13 Low Speed Filter Time Const.	2-** Brakes	4-13 Motor Speed High Limit [RPM]	5-62 Pulse Output Max Freq #27	
1-14 High Speed Filter Time Const.	2-0* DC-Brake	4-14 Motor Speed High Limit [Hz]	5-63 Terminal 29 Pulse Output Variable	
1-15 Voltage filter time const.	2-00 DC Hold/Preheat Current	4-15 Torque Limit Motor Mode	5-65 Pulse Output Max Freq #29	
1-16 Voltage filter time const.	2-01 DC Brake Current	4-16 Torque Limit Generator Mode	5-66 Terminal X30/6 Pulse Output Variable	
1-17 Programming Set-up	2-02 DC Braking Time	4-17 Current Limit	5-68 Pulse Output Max Freq #X30/6	
0-11 Active Set-up	2-03 DC Brake Cut In Speed [RPM]	4-18 Max Output Frequency	5-8* I/O Options	
0-12 This Set-up Linked to	2-04 DC Brake Cut In Speed [Hz]	4-19 Adj. Warnings	5-80 AHF Cap Reconnect Delay	
0-13 Readout: Linked Set-ups	2-06 Parking Current	4-20 Warning Current Low	5-81 Bus Controlled	
0-14 Readout: Prog. Set-ups / Channel	2-07 Parking Time	4-51 Warning Current High	5-90 Digital & Relay Bus Control	
0-2*	LCP Display	2-1* Brake Energy Funt.	5-91 Pulse Out #27 Bus Control	
0-20 Display Line 1.1 Small	2-10 Brake Function	4-52 Warning Speed Low	5-93 Pulse Out #27 Bus Control	
0-21 Display Line 1.2 Small	2-11 Brake Resistor (Ohm)	4-53 Warning Speed High	5-94 Pulse Out #27 Timeout Preset	
0-22 Display Line 1.3 Small	2-12 Brake Power Limit (kW)	4-54 Warning Reference Low	5-95 Pulse Out #29 Bus Control	
0-23 Display Line 2 Large	2-13 Brake Power Monitoring	4-55 Warning Reference High	5-96 Pulse Out #29 Timeout Preset	
0-24 Display Line 3 Large	2-15 Brake Check	4-56 Warning Feedback Low	5-97 Pulse Out #30/6 Bus Control	
0-25 My Personal Menu	2-16 AC brake Max. Current	4-57 Warning Feedback High	5-98 Pulse Out #X30/6 Timeout Preset	
0-3*	LCP Custom Readout	2-17 Over-voltage Control	C-** Analog In/Out	
0-30 Custom Readout Unit	3-** Reference Ramps	4-6* Bypass	6-0* Analog I/O Mode	
0-31 Custom Readout Min Value	3-02 Minimum Reference	4-60 Bypass Speed From [RPM]	6-00 Live Zero Timeout Time	
0-32 Custom Readout Max Value	3-03 Maximum Reference	4-61 Bypass Speed From [Hz]	6-01 Live Zero Timeout Function	
0-37 Display Text 1	3-04 Reference Function	4-62 Bypass Speed To [RPM]	D-** Analog Input 53	
0-38 Display Text 2	3-05 Reference Function	4-63 Bypass Speed To [Hz]	6-11 Terminal 53 Low Voltage	
0-39 Display Text 3	3-06 Main Reactance (Xh)	4-64 Semi-Auto Bypass Set-up	6-12 Terminal 53 High Voltage	
0-4*	LCP Keypad	3-07 Iron Loss Resistance (Rfe)	6-13 Terminal 53 Low Current	
0-40 [Hand on] Key on LCP	3-08 d-axis Inductance (Ld)	6-14 Terminal 53 High Current	6-14 Terminal 53 Low Ref./Feedb. Value	
0-41 [Off/Reset] Key on LCP	3-09 Motor Poles	6-15 Terminal 53 High Ref./Feedb. Value	6-15 Terminal 53 Low Voltage	
0-42 [Auto on] Key on LCP	3-10 Back EMF at 1000 RPM	6-16 Terminal 53 Filter Time Constant	6-16 Terminal 53 Live Zero	
0-43 [Reset] Key on LCP	3-11 Position Detection Gain	6-17 Terminal 53 Live Zero	6-17 Terminal 53 Low Voltage	
0-44 [Off/Reset] Key on LCP	3-12 Reference Site	6-18 Terminal 54 Low Voltage	E-** Analog Input 54	
0-45 [Drive Bypass] Key on LCP	3-13 Preset Relative Reference	6-19 Terminal 54 High Current	6-19 Terminal 54 Low Ref./Feedb. Value	
0-5*	Copy/Save	3-14 Reference 1 Source	6-20 Terminal 54 High Ref./Feedb. Value	
0-50 LCP Copy	3-15 Reference 2 Source	6-21 Terminal 54 Filter Time Constant	6-21 Terminal 54 High Voltage	
0-51 Set-up Copy	3-16 Reference 3 Source	6-22 Terminal 54 Low Current	6-22 Terminal 54 Live Zero	
0-6*	Password	3-17 Jogi Speed [RPM]	6-23 Terminal 54 High Current	
0-67 Bus Password Access	3-18 Motor Magnetisation at Zero Speed	6-24 Terminal 54 Low Ref./Feedb. Value	6-24 Terminal 54 High Ref./Feedb. Value	
0-7*	Clock Settings	3-19 Flystart Test Pulses Current	6-25 Terminal 54 Digital Input	
0-70 Date and Time	3-20 Flystart Test Pulses Frequency	6-26 Terminal 54 Digital Input	6-26 Terminal 54 Filter Time Constant	
0-71 Date Format	3-21 Resonance Dampening	6-27 Terminal 54 Digital Input	6-27 Terminal 54 Live Zero	
0-72 Time Format	3-22 Resonance Dampening Time Constant	6-28 Terminal 32 Digital Input	F-** Analog Input X30/11	
0-74 DST/Summertime	3-23 Min. Current at Low Speed	6-29 Terminal 33 Digital Input	6-30 Terminal X30/11 Low Voltage	
0-76 DST/Summertime Start	3-24 Start Adjustments	6-30 Terminal 27 Digital Output	6-31 Terminal X30/11 High Voltage	
0-77 DST/Summertime End	3-25 Start Mode	6-31 Terminal 29 Digital Output	6-34 Term. X30/11 Low Ref./Feedb. Value	
0-79 Clock Fault	3-26 Start Delay	6-32 Term. X30/6 Digi Out (MCB 101)	6-35 Term. X30/11 High Ref./Feedb. Value	
0-81 Working Days	3-27 Start Function	6-33 Term X30/7 Digi Out	6-36 Term. X30/11 Filter Time Constant	
0-82 Additional Working Days	3-28 Flying Start	6-34 Function Relay	6-37 Term. X30/11 Live Zero	
0-83 Additional Non-Working Days	3-29 Start Speed [RPM]	6-35 On Delay, Relay	G-** Analog Input X30/12	
0-75 Start Current	3-30 Start Speed [Hz]	6-36 Off Delay, Relay	6-40 Terminal X30/12 Low Voltage	
0-76 Start Speed [RPM]	3-31 Ramp Time	6-37 Pulse Input	6-44 Term. X30/12 High Voltage	
0-77 Start Speed [Hz]	3-32 Ramp Time	6-38 Step Size	6-45 Term. X30/12 Low Ref./Feedb. Value	
0-78 Power Restore	3-33 Power Restore	6-39 Digital Pot Meter	6-46 Term. X30/12 High Ref./Feedb. Value	
0-79 Ramp Time	3-34 Power Restore	6-40 Low Frequency	5-52 Term. 29 Low Ref./Feedb. Value	
0-80 Ramp Time	3-35 Power Restore	6-41 High Frequency	5-51 Term. 29 High Frequency	
0-81 Ramp Time	3-36 Power Restore	6-42 Power Restore	5-50 Term. 29 Low Ref./Feedb. Value	

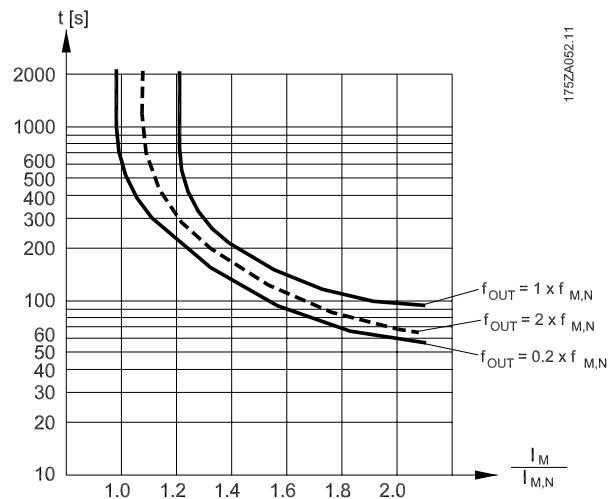
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15-71 Slot A Option SW Version	16-65 Analog Output 42 [mA]	20-21 Setpoint 1	21-43 Ext. 2 Differentiation Time	22-76 Interval between Starts
15-72 Option in Slot B	16-66 Digital Output [bin]	20-22 Setpoint 2	21-44 Ext. 2 Diff. Gain Limit	22-77 Minimum Run Time
15-73 Slot B Option SW Version	16-67 Pulse Input #33 [Hz]	20-23 Setpoint 3	21-5* Ext. CL 3 Ref/FB.	22-78 Minimum Run Time Override Value
15-74 Option in Slot C/E0	16-68 Pulse Input #29 [Hz]	20-7* PID Autotuning	21-51 Ext. 3 Ref./Feedback Unit	22-8* Flow Compensation
15-75 Slot C/E0 Option SW Version	16-69 Pulse Output #27 [Hz]	20-70 Closed Loop Type	21-52 Ext. 3 Minimum Reference	22-80 Flow Compensation
15-76 Option in Slot C/E1	16-70 Pulse Output #29 [Hz]	20-71 PID Performance	21-53 Ext. 3 Maximum Reference	22-81 Square-linear Curve Approximation
15-77 Slot C/E1 Option SW Version	16-71 Relay Output [bin]	20-72 PID Output Change	21-54 Ext. 3 Reference Source	22-82 Work Point Calculation
15-9* Parameter Info	16-72 Counter A	20-73 Minimum Feedback Level	21-55 Ext. 3 Setpoint	22-83 Speed at No-Flow [RPM]
15-92 Defined Parameters	16-73 Counter B	20-74 Maximum Feedback Level	21-56 Ext. 3 Reference [Unit]	22-84 Speed at No-Flow [Hz]
15-93 Modified Parameters	16-75 Analog In X30/11	20-79 PID Autotuning	21-57 Ext. 3 Feedback [Unit]	22-85 Speed at Design Point [RPM]
15-98 Drive Identification	16-76 Analog In X30/12	20-8* PID Basic Settings	21-58 Ext. 3 Output [%]	22-86 Speed at Design Point [Hz]
15-99 Parameter Metadata	16-77 Analog Out X30/8 [mA]	20-81 PID Normal/ Inverse Control	21-59 Ext. CL 3 PID	22-87 Pressure at No-Flow [Speed]
16-** Data Readouts	16-8* Fieldbus & FC Port	20-82 PID Start Speed [RPM]	21-60 Ext. 3 Normal/Inverse Control	22-88 Pressure at Rated Speed
16-0* General Status	16-80 Fieldbus CTW 1	20-83 PID Start Speed [Hz]	21-61 Ext. 3 Proportional Gain	22-89 Flow at Design Point
16-00 Control Word	16-82 Fieldbus REF 1	20-84 On Reference Bandwidth	21-62 Ext. 3 Integral Time	22-90 Flow at Rated Speed
16-01 Reference [Unit]	16-84 Comm. Option STW	20-9* PID Controller	21-63 Ext. 3 Differential Time	23-** Time-based Functions
16-02 Reference [%]	16-85 FC Port CTW 1	20-91 Anti Windup	21-64 Ext. 3 Diff. Gain Limit	23-0* Timed Actions
16-03 Status Word	16-86 FC Port REF 1	20-93 PID Proportional Gain	21-65 Ext. 3 Normal/Inverse Control	23-00 ON Time
16-05 Main Actual Value [%]	16-89 Diagnosis Readouts	20-94 PID Integral Time	21-66 Ext. 3 Normal/Inverse Control	23-01 ON Action
16-09 Custom Readout	16-90 Alarm Word	20-95 PID Differentiation Time	21-67 Ext. 3 Off Action	23-02 OFF Time
16-1* Motor Status	16-91 Alarm Word 2	20-96 PID Diff. Gain Limit	21-68 Ext. 3 Off Action	23-03 OFF Action
16-10 Power [kW]	16-92 Warning Word	21-** Ext. CL Autotuning	21-69 Ext. 3 Occurrence	23-04 Occurrence
16-11 Power [hpl]	16-93 Warning Word 2	21-0* Ext. CL Autotuning	23-1* Maintenance	23-1* Maintenance
16-12 Motor Voltage	16-94 Ext. Status Word	21-00 Closed Loop Type	22-10 Maintenance Item	23-10 Maintenance Item
16-13 Frequency	16-95 Ext. Status Word 2	21-01 PID Performance	22-11 Maintenance Action	23-11 Maintenance Action
16-14 Motor current	16-96 Maintenance Word	21-02 PID Output Change	22-12 Maintenance Time Base	23-12 Maintenance Time Base
16-22 Torque [%]	16-97 Maintenance Log: Item	21-03 Minimum Feedback Level	22-13 Maintenance Time Interval	23-13 Maintenance Time Interval
16-16 Torque [Nm]	16-98 Maintenance Log: Date and Time	21-04 Maximum Feedback Level	22-14 Maintenance Date and Time	23-14 Maintenance Date and Time
16-17 Speed [RPM]	18-00 Maintenance Log: Item	21-09 PID Auto Tuning	23-1* Maintenance Reset	23-1* Maintenance Reset
16-18 Motor Thermal	18-01 Maintenance Log: Time	21-1* Ext. CL 1 Ref/FB.	22-20 Low Power Auto Set-up	23-15 Reset Maintenance Word
16-20 Motor Angle	18-02 Maintenance Log: Date and Time	21-10 Ext. 1 Ref./Feedback Unit	22-21 Low Power Detection	23-16 Maintenance Text
16-22 Torque [%]	18-0* Info & Readouts	21-11 Ext. 1 Minimum Reference	22-22 Low Speed Detection	23-17 Maintenance Text
16-3* Drive Status	18-3* Analog Readouts	21-12 Ext. 1 Maximum Reference	22-23 No-Flow Function	23-18 Trending
16-30 DC Link Voltage	18-30 Analog Input X42/1	21-13 Ext. 1 Reference Source	22-24 No-Flow Delay	23-6* Trending
16-32 Brake Energy /s	18-31 Analog Input X42/3	21-14 Ext. 1 Feedback Source	22-25 No-Flow Power	23-19 Trend Variable
16-33 Brake Energy /2 min	18-32 Analog Input X42/5	21-15 Ext. 1 Setpoint	22-26 Dry Pump Function	23-20 Continuous Bin Data
16-34 Heatsink Temp.	18-33 Analog Out X42/7 [V]	21-17 Ext. 1 Reference [Unit]	22-27 Dry Pump Delay	23-21 Timed Bin Data
16-35 Inverter Thermal	18-34 Analog Out X42/9 [V]	21-18 Ext. 1 Feedback [Unit]	22-28 High Speed [RPM]	23-22 Timed Period Start
16-36 Inv. Nom. Current	18-35 Analog Out X42/11 [V]	21-19 Ext. 1 Output [%]	22-29 High Speed [Hz]	23-23 Timed Period Stop
16-37 Inv. Max. Current	18-36 Analog Input X48/2 [mA]	21-2* Ext. CL 1 PID	22-30 Minimum Run Time	23-24 Minimum Bin Value
16-38 SL Controller State	18-37 Temp. Input X48/4	21-20 Ext. 1 Normal/Inverse Control	22-40 Minimum Sleep Time	23-25 Reset Continuous Bin Data
16-39 Control Card Temp.	18-38 Temp. Input X48/7	21-21 Ext. 1 Proportional Gain	22-41 Maximum Boost Time	23-26 Reset Timed Bin Data
16-40 Logging Buffer Full	18-39 Temp. Input X48/10	21-22 Ext. 1 Integral Time	22-42 Wake-up Speed [RPM]	23-3* Payback Counter
16-49 Current Fault Source	18-6* Inputs & Outputs 2	21-23 Ext. 1 Differentiation Time	22-43 Wake-up Speed [Hz]	23-34 Cost Savings
16-5* Ref. & Feedb.	18-60 Digital Input 2	21-24 Ext. 1 Diff. Gain Limit	22-44 Wake-up Speed [Hz]	23-35 Power Reference Factor
16-50 External Reference	20-** Drive Closed Loop	21-3* Ext. CL 2 Ref/FB.	22-45 Wake-up Speed [FB Difference]	24-1* Drive Bypass
16-52 Feedback 1 [Unit]	20-0* Feedback 1 Source	21-30 Ext. 2 Ref./Feedback Unit	22-46 Setpoint Boost	23-36 Investment
16-53 Digi Pot Reference	20-01 Feedback 1 Conversion	21-31 Ext. 2 Minimum Reference	22-47 Broken Belt Function	23-37 Energy Cost
16-54 Feedback 1 [Unit]	20-02 Feedback 1 Source Unit	21-32 Ext. 2 Maximum Reference	22-48 Broken Belt Torque	23-38 Cost Savings
16-55 Feedback 2 [Unit]	20-03 Feedback 2 Source	21-33 Ext. 2 Reference Source	22-49 Broken Belt Function	23-39 Drive Bypass
16-56 Feedback 3 [Unit]	20-04 Feedback 2 Conversion	21-34 Ext. 2 Setpoint	22-50 End of Curve Function	25-3* Cascade Controller
16-58 PID Output [%]	20-05 Feedback 2 Source Unit	21-35 Ext. 2 Reference [Unit]	22-51 End of Curve Delay	25-4* System Settings
16-59 Adjusted Setpoint	20-06 Feedback 3 Source	21-36 Ext. 2 Feedback [Unit]	22-52 Broken Belt Function	25-50 Cascade Controller
16-6* Inputs & Outputs	20-07 Feedback 3 Conversion	21-37 Ext. 2 Output [%]	22-53 Broken Belt Torque	
16-60 Digital Input	20-08 Feedback 3 Source Unit	21-38 Ext. 2 Output	22-54 Broken Belt Function	
16-61 Terminal 53 Switch Setting	20-12 Reference/Feedback Unit	21-40 Ext. 2 Normal/Inverse Control	22-55 Broken Belt Delay	
16-62 Analog Input 53	20-20 Feedback Function	21-41 Ext. 2 Proportional Gain	22-56 Short Cycle Protection	
16-63 Terminal 54 Switch Setting	20-20 Feedback Function	21-42 Ext. 2 Integral Time	22-57 Short Cycle Protection	
16-64 Analog Input 54				

25-02	Motor Start	26-20	Terminal X42/3 Low Voltage	27-34	Stage Off Speed [Hz]
25-04	Pump Cycling	26-21	Terminal X42/3 High Voltage	27-4*	Staging Settings
25-05	Fixed Lead Pump	26-24	Term. X42/3 Low Ref./Feedb. Value	27-40	Auto Tune Staging Settings
25-06	Number of Pumps	26-25	Term. X42/3 High Ref./Feedb. Value	27-41	Ramp Down Delay
25-2*	Bandwidth Settings	26-26	Term. X42/3 Filter Time Constant	27-42	Ramp Up Delay
25-20	Staging Bandwidth	26-27	Term. X42/3 Live Zero	27-43	Staging Threshold
25-21	Override Bandwidth	26-3*	Analog Input X42/5	27-44	Destaging Threshold
25-22	Fixed Speed Bandwidth	26-30	Terminal X42/5 Low Voltage	27-45	Staging Speed [Hz]
25-23	SBW Staging Delay	26-31	Terminal X42/5 High Voltage	27-46	Destaging Speed [Hz]
25-24	SBW Destaging Delay	26-34	Term. X42/5 Low Ref./Feedb. Value	27-47	Destaging Speed [RPM]
25-25	OBW Time	26-35	Term. X42/5 High Ref./Feedb. Value	27-48	Destaging Speed [Hz]
25-26	Destage At No-Flow	26-36	Term. X42/5 Filter Time Constant	27-5*	Alternate Settings
25-27	Stage Function	26-37	Term. X42/5 Live Zero	27-50	Automatic Alternation
25-28	Stage Function Time	26-4*	Analog Out X42/7	27-51	Alternation Event
25-29	Destage Function	26-40	Terminal X42/7 Output	27-52	Alternation Time Interval
25-30	Destage Function Time	26-41	Terminal X42/7 Min. Scale	27-53	Alternation Timer Value
25-4*	Staging Settings	26-42	Terminal X42/7 Bus Control	27-54	Alternation At Time of Day
25-40	Ramp Down Delay	26-43	Terminal X42/7 Timeout Preset	27-55	Alternation Predefined Time
25-41	Ramp Up Delay	26-44	Terminal X42/7 Timeout Preset	27-56	Alternate Capacity is <
25-42	Staging Threshold	26-5*	Analog Out X42/9	27-58	Run Next Pump Delay
25-43	Destaging Threshold	26-50	Terminal X42/9 Output	27-6*	Digital Inputs
25-44	Staging Speed [RPM]	26-51	Terminal X42/9 Min. Scale	27-60	Terminal X66/1 Digital Input
25-45	Staging Speed [Hz]	26-52	Terminal X42/9 Max. Scale	27-61	Terminal X66/3 Digital Input
25-46	Destaging Speed [RPM]	26-53	Terminal X42/9 Bus Control	27-62	Terminal X66/5 Digital Input
25-47	Destaging Speed [Hz]	26-54	Terminal X42/9 Timeout Preset	27-63	Terminal X66/7 Digital Input
25-5*	Alternation Settings	26-6*	Analog Out X42/11	27-64	Terminal X66/9 Digital Input
25-50	Lead Pump Alternation	26-60	Terminal X42/11 Output	27-65	Terminal X66/11 Digital Input
25-51	Alternation Event	26-61	Terminal X42/11 Min. Scale	27-66	Terminal X66/13 Digital Input
25-52	Alternation Time Interval	26-62	Terminal X42/11 Max. Scale	27-7*	Connections
25-53	Alternation Timer Value	26-63	Terminal X42/11 Bus Control	27-70	Relay
25-54	Alternation Predefined Time	26-64	Terminal X42/11 Timeout Preset	27-9*	Readouts
25-55	Alternate If Load < 50%			27-91	Cascade Reference
25-56	Staging Mode at Alternation			27-92	% Of Total Capacity
25-58	Run Next Pump Delay			27-93	Cascade Option Status
25-59	Run on Mains Delay			27-94	Cascade System Status
25-8*	Status			27-95	Advanced Cascade Relay Output [bin]
25-80	Cascade Status			27-96	Extended Cascade Relay Output [bin]
25-81	Pump Status			29-2*	Water Application Functions
25-82	Lead Pump			29-0	Pipe Fill
25-83	Relay Status			29-00	Pipe Fill Enable
25-84	Pump ON Time			29-01	Pipe Fill Speed [RPM]
25-85	Relay ON Time			29-02	Pipe Fill Speed [Hz]
25-86	Reset Relay Counters			29-03	Pipe Fill Time
25-9*	Service			29-04	Pipe Fill Rate
25-90	Pump Interlock			29-05	Filled Setpoint
25-91	Manual Alternation			29-06	No-Flow Disable Timer
26-**	Analog I/O Option	27-2*	Bandwidth Settings	29-1*	Deraging Functions
26-0*	Analog I/O Mode	27-0	Normal Operating Range	29-10	Derag Cycles
26-00	Terminal X42/1 Mode	27-21	Override Limit	29-11	Derag at Start/Stop
26-01	Terminal X42/3 Mode	27-22	Fixed Speed Only Operating Range	29-12	Deraging Run Time
26-02	Terminal X42/5 Mode	27-23	Staging Delay	29-13	Derag Speed [RPM]
26-10	Terminal X42/1 Low Voltage	27-24	Destaging Delay	29-14	Derag Speed [Hz]
26-11	Terminal X42/1 High Voltage	27-25	Override Hold Time	29-15	Derag Off Delay
26-15	Term. X42/1 Low Ref./Feedb. Value	27-27	Min Speed Destage Delay	29-2*	Derag Power Tuning
26-16	Term. X42/1 High Ref./Feedb. Value	27-30	Auto Tune Staging Spreads	29-21	Derag Power [kW]
26-17	Term. X42/1 Filter Time Constant	27-31	Stage On Speed [RPM]	29-22	Derag Power Factor
26-18	Term. X42/1 Live Zero	27-32	Stage On Speed [Hz]	29-23	Derag Power Delay
26-2*	Analog Input X42/3	27-33	Stage Off Speed [RPM]	29-24	Low Speed [RPM]

Motor Thermal Protection

This is the way Danfoss is protecting the motor from being overheated. It is an electronic feature that simulates a bimetal relay based on internal measurements. The characteristic is shown in the following figure:



175ZA052.11

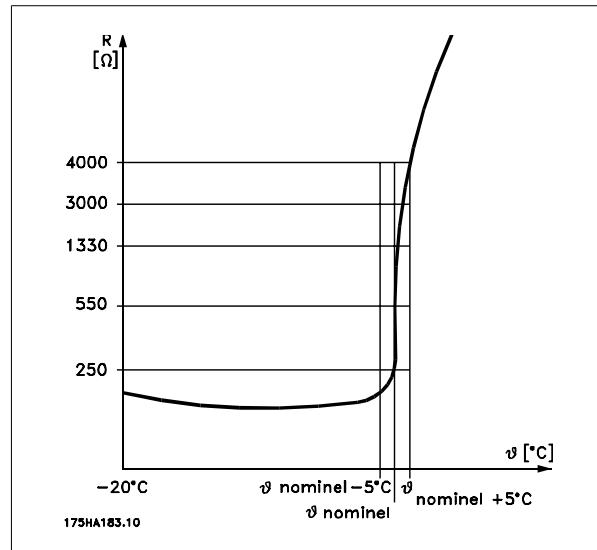
Illustration 2.6: The X-axis is showing the ratio between I_{motor} and I_{motor} nominal. The Y- axis is showing the time in seconds before the ETR cuts off and trips the drive. The curves are showing the characteristic nominal speed at twice the nominal speed and at 0,2x the nominal speed.

It is clear that at lower speed the ETR cuts off at lower heat due to less cooling of the motor. In that way the motor are protected from being over heated even at low speed. The ETR feature is calculating the motor temperature based on actual current and speed. The calculated temperature is visible as a read out parameter in par. 16-18 *Motor Thermal* in the frequency converter.

The thermistor cut-out value is $> 3 \text{ k}\Omega$.

Integrate a thermistor (PTC sensor) in the motor for winding protection.

Motor protection can be implemented using a range of techniques: PTC sensor in motor windings; mechanical thermal switch (Klixon type); or Electronic Thermal Relay (ETR).



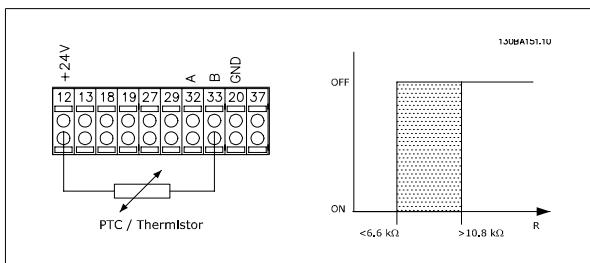
Using a digital input and 24 V as power supply:

Example: The frequency converter trips when the motor temperature is too high.

Parameter set-up:

Set par. 1-90 *Motor Thermal Protection to Thermistor Trip* [2]

Set par. 1-93 *Thermistor Source to Digital Input 33* [6]



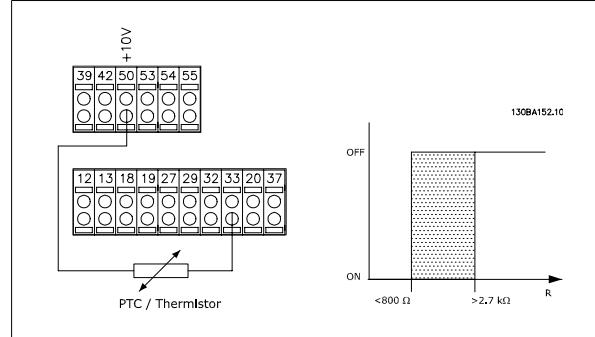
Using a digital input and 10 V as power supply:

Example: The frequency converter trips when the motor temperature is too high.

Parameter set-up:

Set par. 1-90 *Motor Thermal Protection to Thermistor Trip* [2]

Set par. 1-93 *Thermistor Source to Digital Input 33* [6]



Using an analog input and 10 V as power supply:

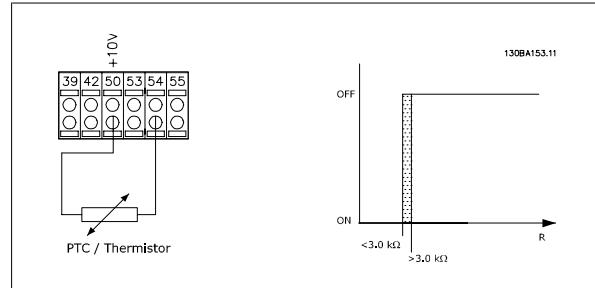
Example: The frequency converter trips when the motor temperature is too high.

Parameter set-up:

Set par. 1-90 *Motor Thermal Protection to Thermistor Trip* [2]

Set par. 1-93 *Thermistor Source to Analog Input 54* [2]

Do not select a reference source.



Input	Supply Voltage	Threshold
Digital/analog	Volt	Cut-out Values
Digital	24 V	< 6.6 kΩ - > 10.8 kΩ
Digital	10 V	< 800 Ω - > 2.7 kΩ
Analog	10 V	< 3.0 kΩ - > 3.0 kΩ



NB!

Check that the chosen supply voltage follows the specification of the used thermistor element.

Summary

With the Torque limit feature the motor is protected for being overloaded independent of the speed. With the ETR the motor is protected for being over heated and there is no need for any further motor protection. That means when the motor is heated up the ETR timer controls for how long time the motor can be running at the high temperature before it is stopped in order to prevent over heating. If the motor is overloaded without reaching the temperature where the ETR shuts off the motor, the torque limit is protecting the motor and application for being overloaded.

NB!

ETR is activated in par. and is controlled in par. 4-16 *Torque Limit Motor Mode*. The time before the torque limit warning trips the frequency converter is set in par. 14-25 *Trip Delay at Torque Limit*.

Troubleshooting

Warnings/Alarm Messages

A warning or an alarm is signalled by the relevant LED on the front of the frequency converter and indicated by a code on the display.

A warning remains active until its cause is no longer present. Under certain circumstances operation of the motor may still be continued. Warning messages may be critical, but are not necessarily so.

In the event of an alarm, the frequency converter will have tripped. Alarms must be reset to restart operation once their cause has been rectified.

This may be done in three ways

- By pressing [Reset].
- Via a digital input with the "Reset" function.
- Via serial communication/optional fieldbus.

NOTE

After a manual reset pressing [Reset], [Auto On] must be pressed to restart the motor.

If an alarm cannot be reset, the reason may be that its cause has not been rectified, or the alarm is trip-locked (see also *Table 5.1*).

Alarms that are trip-locked offer additional protection, meaning that the mains supply must be switched off before the alarm can be reset. After being switched back on, the frequency converter is no longer blocked and may be reset as described above once the cause has been rectified.

Alarms that are not trip-locked can also be reset using the automatic reset function in **14-20 Reset Mode** (Warning: automatic wake-up is possible!)

If a warning and alarm is marked against a code in *Table 5.1*, this means that either a warning occurs before an alarm, or else that it is possible to specify whether it is a warning or an alarm that is to be displayed for a given fault.

This is possible, for instance, in **1-90 Motor Thermal Protection**. After an alarm or trip, the motor carries on coasting, and the alarm and warning flash. Once the problem has been rectified, only the alarm continues flashing until the frequency converter is reset.

NOTE

No missing motor phase detection (no 30-32) and no stall detection is active when **1-10 Motor Construction** is set to **[1] PM non salient SPM**.

No.	Description	Warning	Alarm/Trip	Alarm/Trip Lock	Parameter Reference
1	10 Volts low	X			
2	Live zero error	(X)	(X)		6-01 Live Zero Timeout Function
3	No motor	(X)			1-80 Function at Stop
4	Mains phase loss	(X)	(X)	(X)	14-12 Function at Mains Imbalance
5	DC link voltage high	X			
6	DC link voltage low	X			
7	DC over-voltage	X	X		
8	DC under voltage	X	X		
9	Inverter overloaded	X	X		
10	Motor ETR over temperature	(X)	(X)		1-90 Motor Thermal Protection
11	Motor thermistor over temperature	(X)	(X)		1-90 Motor Thermal Protection
12	Torque limit	X	X		
13	Over Current	X	X	X	

No.	Description	Warning	Alarm/Trip	Alarm/Trip Lock	Parameter Reference
14	Earth Fault	X	X	X	
15	Hardware mismatch		X	X	
16	Short Circuit		X	X	
17	Control word time-out	(X)	(X)		8-04 Control Timeout Function
20	Temp. Input Error				
21	Param Error				
22	Hoist Mech. Brake	(X)	(X)		Parameter group 2-2*
23	Internal Fans	X			
24	External Fans	X			
25	Brake resistor short-circuited	X			
26	Brake resistor power limit	(X)	(X)		2-13 Brake Power Monitoring
27	Brake chopper short-circuited	X	X		
28	Brake check	(X)	(X)		2-15 Brake Check
29	Heatsink temp	X	X	X	
30	Motor phase U missing	(X)	(X)	(X)	4-58 Missing Motor Phase Function
31	Motor phase V missing	(X)	(X)	(X)	4-58 Missing Motor Phase Function
32	Motor phase W missing	(X)	(X)	(X)	4-58 Missing Motor Phase Function
33	Inrush Fault		X	X	
34	Fieldbus communication fault	X	X		
35	Option Fault				
36	Mains failure	X	X		
37	Phase imbalance		X		
38	Internal Fault		X	X	
39	Heatsink sensor		X	X	
40	Overload of Digital Output Terminal 27	(X)			5-00 Digital I/O Mode, 5-01 Terminal 27 Mode
41	Overload of Digital Output Terminal 29	(X)			5-00 Digital I/O Mode, 5-02 Terminal 29 Mode
42	Ovrld X30/6-7	(X)			
43	Ext. Supply (option)				
45	Earth Fault 2	X	X	X	
46	Pwr. card supply		X	X	
47	24 V supply low	X	X	X	
48	1.8 V supply low		X	X	
49	Speed limit	X			
50	AMA calibration failed		X		
51	AMA check U_{nom} and I_{nom}		X		
52	AMA low I_{nom}		X		
53	AMA motor too big		X		
54	AMA motor too small		X		
55	AMA parameter out of range		X		
56	AMA interrupted by user		X		
57	AMA time-out		X		
58	AMA internal fault	X	X		
59	Current limit	X			
60	External Interlock	X	X		

No.	Description	Warning	Alarm/Trip	Alarm/Trip Lock	Parameter Reference
61	Feedback Error	(X)	(X)		4-30 Motor Feedback Loss Function
62	Output Frequency at Maximum Limit	X			
63	Mechanical Brake Low		(X)		2-20 Release Brake Current
64	Voltage Limit	X			
65	Control Board Over-temperature	X	X	X	
66	Heat sink Temperature Low	X			
67	Option Configuration has Changed		X		
68	Safe Stop	(X)	(X) ¹⁾		5-19 Terminal 37 Digital Input
69	Pwr. Card Temp		X	X	
70	Illegal FC configuration			X	
71	PTC 1 Safe Stop				
72	Dangerous failure				
73	Safe Stop Auto Restart	(X)	(X)		5-19 Terminal 37 Digital Input
74	PTC Thermistor			X	
75	Illegal Profile Sel.		X		
76	Power Unit Setup	X			
77	Reduced power mode	X			14-59 Actual Number of Inverter Units
78	Tracking Error	(X)	(X)		4-34 Tracking Error Function
79	Illegal PS config		X	X	
80	Drive Initialized to Default Value		X		
81	CSIV corrupt		X		
82	CSIV parameter error		X		
83	Illegal Option Combination			X	
84	No Safety Option		X		
88	Option Detection			X	
89	Mechanical Brake Sliding	X			
90	Feedback Monitor	(X)	(X)		17-61 Feedback Signal Monitoring
91	Analog input 54 wrong settings			X	S202
163	ATEX ETR cur.lim.warning	X			
164	ATEX ETR cur.lim.alarm		X		
165	ATEX ETR freq.lim.warning	X			
166	ATEX ETR freq.lim.alarm		X		
250	New spare parts			X	
251	New Type Code		X	X	

Table 5.1 Alarm/Warning Code List

(X) Dependent on parameter

1) Can not be Auto reset via 14-20 Reset Mode

A trip is the action when an alarm has appeared. The trip will coast the motor and can be reset by pressing [Reset] or make a reset by a digital input (parameter group 5-1* [1]). The origin event that caused an alarm cannot damage the frequency converter or cause dangerous conditions. A trip lock is an action when an alarm occurs, which may

damage the frequency converter or connected parts. A Trip Lock situation can only be reset by a power cycling.

LED indication	
Warning	yellow
Alarm	flashing red
Trip locked	yellow and red

Table 5.2